Table. Range of variation in landscape structure for Ponderosa Pine-Oak-Aspen Forest under the simulated HRV disturbance scenario on the Uncompahgre Plateau Landscape, Colorado, and the degree of departure of the current landscape from the simulated range of variation (see text for details).

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¹ Percentile of HRV is the position of the current landscape in the simulated distribution.
² CV² is the coefficient of variation squared.
³ Departure Index is the degree of departure of the current landscape from the simulated range of variation.
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Summary Indices:

<table>
<thead>
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<th>Index</th>
<th>Value</th>
</tr>
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<tbody>
<tr>
<td>Seral-Stage Departure Index</td>
<td>96</td>
</tr>
<tr>
<td>Class Configuration Departure Index</td>
<td>90</td>
</tr>
<tr>
<td>Cover Type Departure Index</td>
<td>93</td>
</tr>
</tbody>
</table>

1. Some stand conditions are not represented in the current landscape. Certain metrics are logically zero if the class is absent, while others are undefined (indicated by missing data). HRV departure index is undefined if the current landscape condition is undefined.

2. CV = coefficient of variation in the simulated distribution, computed as the difference between the 5 and 95th percentiles divided by the median and multiplied by 100 to convert to a percentage. n/d = not defined (division by zero).

3. HRV departure index represents the degree of departure of the current landscape condition from the historic range of variability and is given here specifically as the degree of departure from the 25-75th percentile range of variation, where a 0 represents no departure (i.e., within the 25-75th percentiles of variation) and 100 represents complete departure (i.e., outside the 0-100th percentiles of variation).

4. Landscape composition here represents the distribution of area among seral stages for the corresponding cover type. PLAND = the percent of the landscape encompassed by the corresponding seral stage. Note, PLAND = the percentage of the entire landscape, not as a percent of the corresponding cover type.

5. Landscape configuration here represents the spatial character, distribution, and arrangement of the corresponding cover type. The landscape metrics listed here are described in detail in the FRAGSTATS methods section. PD = patch density; ED = edge density; AREA_MN = mean patch size; AREA_AM = area-weighted mean patch size; GYRATE_AM = area-weighted mean patch radius of gyration (correlation length); SHAPE_MN = mean patch shape index; SHAPE_AM = area-weighted mean patch shape index; CPLAND = core area percent of landscape; CORE_MN = mean patch core area; CORE_AM = area-weighted mean patch core area; CAI_MN = mean patch core area index; CAI_AM = area-weighted mean patch core area index; PROX_MN = mean proximity index; PROX_AM = area-weighted mean proximity index; CWED = contrast-weighted edge density; TECI = total edge contrast index; CLUMPY = clumpiness index; IJI = interspersion and juxtaposition index.

6. Seral-stage departure index is based on the distribution of area (percentage of landscape) among seral stages and is computed as the mean departure across seral stages. Class configuration departure index is based on several landscape metrics that quantify different aspects of the spatial distribution of the cover type and is computed as the mean departure across metrics. Cover type departure index is computed as the mean of the seral-stage and class configuration departure indices.